

# Embedded With Rust

Writing Embedded Software Using  
The Rust Programming Language

Jacob Creedon

# What's wrong with C/C++?

- Problems with C/C++

- Unsafe by default
- Safety guidelines exist, (e.g. MISRA) but they require proprietary (and expensive) static analysis tools.
- Tooling can require a lot of work to configure

- New systems programming language contenders

- Go (Sponsored by Google)
- D (Based on C++)
- Rust (Sponsored by Mozilla)

Should I be starting a  
new codebase in C/C++?

What about embedded?

With Rust, maybe...

# Why Rust?

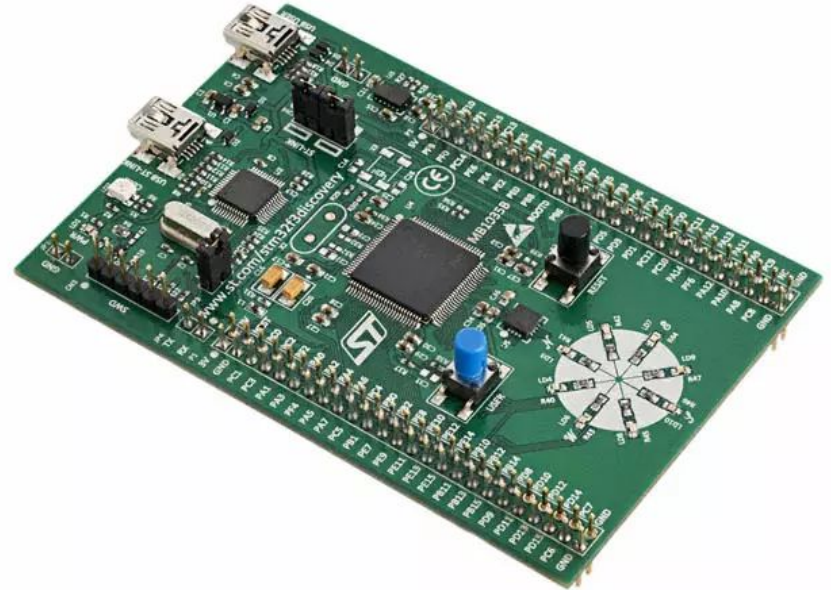
- Zero-cost/low-cost abstractions (just like C++)
- Reduction of undefined behavior
- Focused on concurrency and memory safety
- Safe by default
- Ownership, borrowing, lifetimes
- No garbage collection
- Excellent build system and package manager (Cargo)

# Project - MIDI Controller

- I need a little extra control when doing live events
  - First get a blinking light
  - Then get fader readings
- Outline
    - Hardware
    - Setup Dev Environment
    - Ecosystem Overview
    - Write Code
    - Flash and debug

# Hardware Platform

- ST Micro F3 Discovery
- ~\$15 from Digikey
- STM32F303VCT6
- 8 LEDs
- Accelerometer
- On board debugger





# Install Rust and Toolchains

- Download and run rustup  
([www.rustup.rs](http://www.rustup.rs))
  - Rustup is the toolchain manager
- Install the nightly toolchain
- Install GCC toolchain for arm-none-eabi-
  - This is to get GDB
- Install GDB Server as needed
  - OpenOCD, JLink, etc.
  - Or just use a Black Magic Probe
- Install Editor or IDE
  - Visual Studio Code
    - “Rust (rls)” Plugin
  - IntelliJ IDEA
    - IntelliJ-rust plugin

# Cargo, Crates, and Layers of Abstraction

Architecture

Device

HAL

Driver

BSP

- Cargo is the Rust package manager and build system
- Packages are called “Crates”
- Downloads and builds dependencies then builds your project

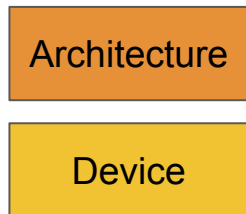
- Architecture Crate
- Device Crate
- Board Support Crate
- HAL Implementation Crate
- Driver Crate

# Cargo, Crates, and Layers of Abstraction



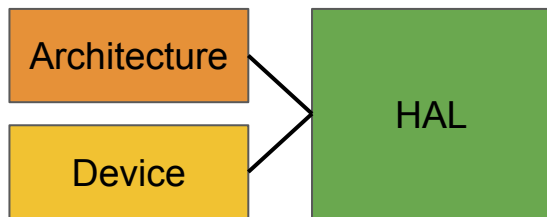
- Registers common to the architecture
- Example, Cortex-M:
  - SYSTICK
  - ITM
  - etc.

# Cargo, Crates, and Layers of Abstraction



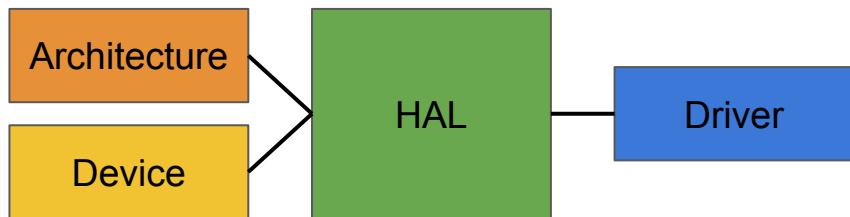
- Registers specific to the chip and its peripherals
- Crates can be auto-generated from SVD files
- Depending on the SVD, registers have meaningful names with named bitfields

# Cargo, Crates, and Layers of Abstraction



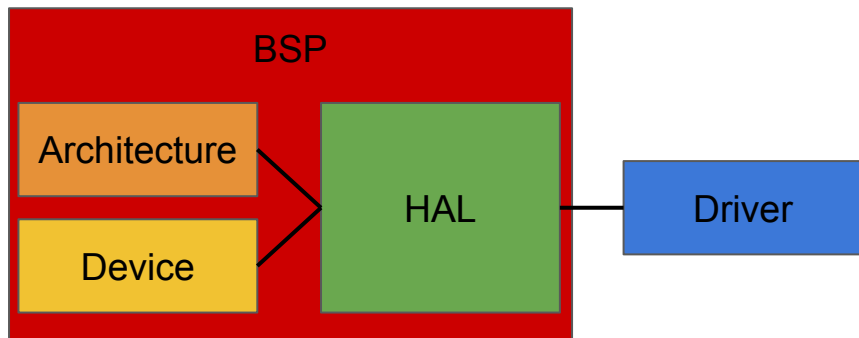
- Abstraction on top of common device peripherals to provide a consistent interface, e.g.:
  - SPI, I2C, Serial
- This is kind of like how Arduino acts as a HAL
- Implement logic not represented in SVD File

# Cargo, Crates, and Layers of Abstraction



- Drivers for external components accessible via the HAL
- Example: a LSM303DLHC I2C Accelerometer driver uses the HAL

# Cargo, Crates, and Layers of Abstraction



- Acts as a collection of crates necessary for working with a particular development board
- Often has aliases for board features e.g. led -> PC13
- Very few of these around, but useful for hitting the ground running if available

# Write Code

```
#![no_std]
#![deny(unsafe code)]
#![deny(warnings)]

extern crate cortex_m;
extern crate f3;
extern crate panic_abort;

use f3::hal::stm32f30x;
use f3::hal::prelude::*;
use f3::hal::delay::Delay;
use f3::led::Leds;

fn main() {
    let cortex_peripherals = cortex_m::Peripherals::take().unwrap();
    let stm_peripherals = stm32f30x::Peripherals::take().unwrap();

    let mut flash = stm_peripherals.FLASH.constrain();
    let mut rcc = stm_peripherals.RCC.constrain();
    let gpioe = stm_peripherals.GPIOE.split((mut rcc.ahb);

    let clocks = rcc.cfgr.freeze((mut flash.acr);
    let mut leds = Leds::new(gpioe);
    let mut delay = Delay::new(cortex_peripherals.SYST_clocks);

    loop {
        leds[0].on();
        delay.delay_ms(600_u16);
        leds[0].off();
        delay.delay_ms(600_u16);
    }
}
```



# Write Code - Imports

Architecture

BSP

```
extern crate cortex_m;  
extern crate f3;  
extern crate panic_abort;
```

```
use f3::hal::stm32f30x;  
use f3::hal::prelude::*;  
use f3::hal::delay::Delay;  
use f3::led::Leds;
```

Device

HAL

# Write Code - Initialization

```
let cortex_peripherals = cortex_m::Peripherals::take().unwrap() ;
let stm_peripherals = stm32f30x::Peripherals::take().unwrap() ;

let mut flash = stm_peripherals.FLASH.constrain() ;
let mut rcc = stm_peripherals.RCC.constrain() ;
let gpioe = stm_peripherals.GPIOE.split(& mut rcc.ahb) ;

let clocks = rcc.cfgr.freeze(& mut flash.acr) ;
let mut delay = Delay::new(cortex_peripherals.SYST , clocks) ;
let mut leds = Leds::new(gpioe) ;
```

Architecture

Device

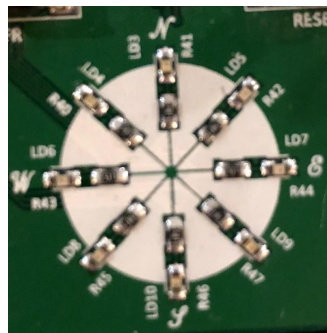
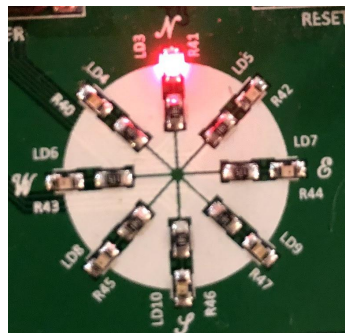
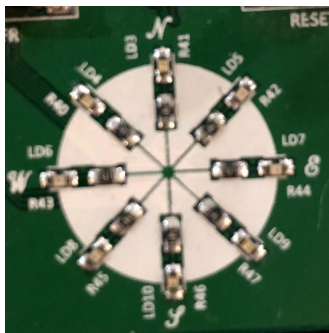
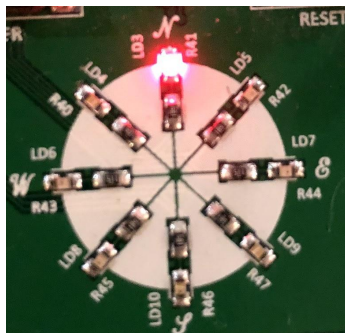
HAL

# Write Code - Main Loop

```
loop {  
    leds[0].on();  
    delay.delay_ms(500_u16);  
    leds[0].off();  
    delay.delay_ms(500_u16);  
}
```

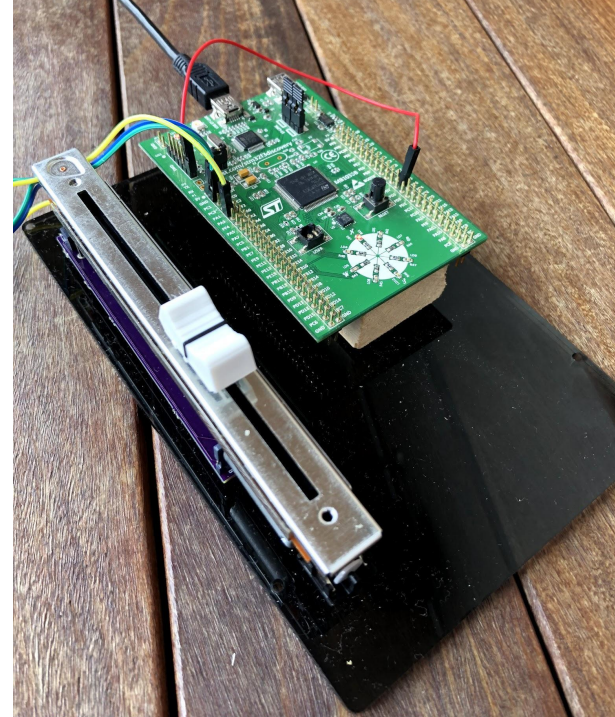
# Build, Flash, Debug

- cargo build
- openocd -f interface/stlink.cfg -f target/stm32f3x.cfg
- arm-none-eabi-gdb target/thumbv7em-none-eabihf/debug/blinky
  - target remote :3333
  - load
  - continue



# Hardware Platform - Part 2

- STM32F3DISCOVERY
- 100mm Slide Pot
- Let's read a value and print it



# Setting a Register

```
let adc1 = stm_peripherals.ADC1;

adc1.cfgr.modify(|_, w| {
    w.align().clear_bit(); // Right data alignment
    w.cont().clear_bit(); // Single conversion mode
    w.ovrmod().set_bit() // Overwrite
});
```

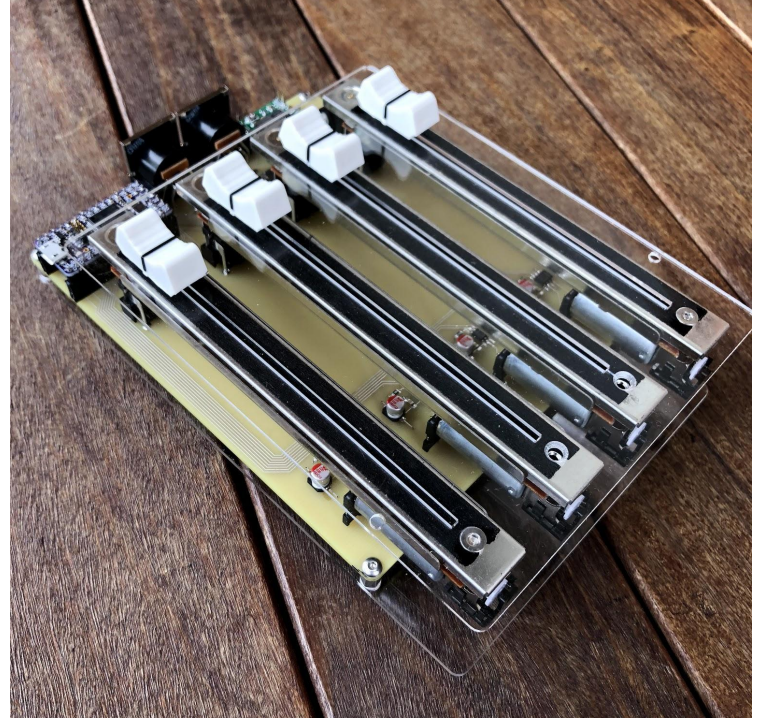
# Reading a Register

```
let mut itm = cortex_peripherals.ITM;
loop {
    adc1.cr.modify(|_, w| w.adstart().set_bit());
    while !adc1.isr.read().eos().bit() {}
    value = adc1.dr.read().regular_data().bits();
    adc1.isr.modify(|_, w| {
        w.eoc().clear_bit();
        w.eos().clear_bit()
    });
    iprintln!(&mut itm.stim[0], "Value {}", value)
    delay.delay_ms(500_u16);
}
```

Value 2479  
Value 2135  
Value 1851  
Value 1597  
Value 1418  
Value 1272  
Value 1105  
Value 881  
Value 574  
Value 209  
Value 0  
Value 2  
Value 4  
Value 2  
Value 6  
Value 5  
Value 6  
Value 204  
Value 540  
Value 857  
Value 1147  
Value 1501  
Value 2003  
Value 2569

# Hardware Platform - Part 3

- 1Bitsy
- MIDI In & Out
- 4 Motorized Faders





# Why Not Rust?

- Still unstable, breaking changes still occur occasionally
- Examples are limited. What is available is often outdated because of the above
- Ecosystem is young and leans heavily towards Cortex-M, and then towards STM32

# What to look forward to

- Embedded hitting Rust stable this year
- AVR support soon (already in LLVM trunk)
- Documentation is growing

# Thank You

Jacob Creedon

@jacobcreedon  
jcreedon@gmail.com

Questions?